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## ABSTRACT (CURRENTLY AMMENDED)

A system (1') of tracking camera for acquiring and 5 transmitting, in real time, data representing the position in space, in terms of spatial coordinates and inclination with respect to a reference point, of a video camera (10'), while the camera moves along a trajectory is presented. thus acquired, once processed, The data 10 determination of the position and inclination of the images obtained. It consists of two principal subsystems: a module containing an inertial sensing unit (11') to be attached to a professional video camera (10') and a module for data processing using stored software programs (2), 15 communicating with the inertial sensing unit via a connection (112'), either wired or wireless. applications in the integration of images captured by the camera with images from other sources and in navigation within a virtual universe. 20

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